

STUDY MODULE DESCRIPTION FORM		
Name of the module/subject Control of Mechatronic Systems		Code 1010321361010326006
Field of study Electrical Engineering	Profile of study (general academic, practical) (brak)	Year /Semester 3 / 6
Elective path/specialty Electrical Systems in Mechatronics	Subject offered in: Polish	Course (compulsory, elective) obligatory
Cycle of study: First-cycle studies	Form of study (full-time, part-time) full-time	
No. of hours Lecture: 30 Classes: - Laboratory: - Project/seminars: 15		No. of credits 3
Status of the course in the study program (Basic, major, other) (brak)		(university-wide, from another field) (brak)
Education areas and fields of science and art technical sciences Technical sciences		ECTS distribution (number and %) 3 100% 3 100%
Responsible for subject / lecturer: Ph. D. Wiesław Łyskawiński email: Wieslaw.Lyskawinski@put.poznan.pl tel. 61 665 2781 Faculty of Electrical Engineering ul. Piotrowo 3A 60-965 Poznań		Responsible for subject / lecturer: Ph. D. Cezary Jędrzycka email: Cezary.Jedryczka@put.poznan.pl tel. 61 647 5803 Faculty of Electrical Engineering ul. Piotrowo 3A 60-965 Poznań
Prerequisites in terms of knowledge, skills and social competencies:		
1	Knowledge	Elementary knowledge of electrical machines, power electronics and control theory
2	Skills	Principles of programming on a general level. Skill of effective self-education in a field related to the chosen field of study
3	Social competencies	Students are aware of the need to expand their competences, readiness to cooperate in a team
Assumptions and objectives of the course: The Student should obtain the knowledge of structures and control methods applied in the mechatronic systems, competences in the analysis and synthesis of these systems. Student will learn elaborate algorithms and develop programs for the control systems of selected processes by using programmable logic controllers.		
Study outcomes and reference to the educational results for a field of study		
Knowledge: 1. distinguish the structures and control methods of mechatronic systems and able to characterize the principle of operation of automatic control systems of speed, torque and displacement - [K_W22+++]		
Skills: 1. can formulate rules for cascade control, modular and symmetrical optimization criteria and apply direct and indirect control of flux and torque and vector control - [K_U10++]		
Social competencies: 1. able to think and act in an entrepreneurial manner in the area of automation of mechatronic systems - [K_K04++]		
Assessment methods of study outcomes		

<p>Lecture</p> <ul style="list-style-type: none"> - assessment of the knowledge and skills on basis of the written exam - focused on solving practical problem (student may use any teaching materials); - continuous evaluation on each course (rewarding activity and quality of the perception). <p>Project:</p> <ul style="list-style-type: none"> - assessment based on the current progress of the project tasks <p>Extra points for the activity in the classroom, in particular for:</p> <ul style="list-style-type: none"> - proposals to discuss supplementary aspects of the subject; - effectiveness of the application of the knowledge gained during solving the given problem; - comments related to the improvement of teaching materials; - quality and diligence of the developed reports - in the self-study. 		
Course description		
<p>General control structure of mechatronic system ? requirements and problems. Structures and mathematical models of the dc converter-fed drive. Principles of synthesis of the cascade control structure, criterion of the optimum module as well as the symmetrical criterion. Reverse structures of the dc drive systems, two-zone speed control. Speed control systems of the squirrel-cage and slip-ring asynchronous machines, mathematical models, direct as well as indirect flux and torque control, vector control methods. Speed control systems of the synchronous motors, mathematical models, flux and torque control structures. Position control systems ? electric servo drives.</p>		
<p>Basic bibliography:</p> <ol style="list-style-type: none"> 1. Deskur J., Kaczmarek T., Zawirski K., Automatyka napędu elektrycznego, Wydawnictwo Politechniki Poznańskiej, Poznań 2012. 2. Napęd elektryczny robotów, Wyd.2, Kaczmarek T., Wyd. Politechniki Poznańskiej, Poznań, 1998. 3. Układy napędowe z silnikami synchronicznymi , Kaczmarek T., Zawirski K., Wyd. PP, Poznań, 2000. 		
<p>Additional bibliography:</p> <ol style="list-style-type: none"> 1. Automatyka napędu przekształtnikowego, Tunia H., Kaźmierkowski M.P., PWN, Warszawa, 1988. 2. Control of Electrical Drives, Leonhard W., Springer-Verlag, Berlin-Heidelberg-NewYork-Tokyo, 1985 		
Result of average student's workload		
Activity	Time (working hours)	
1. participation in lecture classes	30	
2. participation in project classes	15	
3. participate in the consultations	10	
4. implementation of project tasks	15	
5. exam preparation	20	
6. exam	2	
Student's workload		
Source of workload	hours	ECTS
Total workload	92	3
Contact hours	57	2
Practical activities	30	1